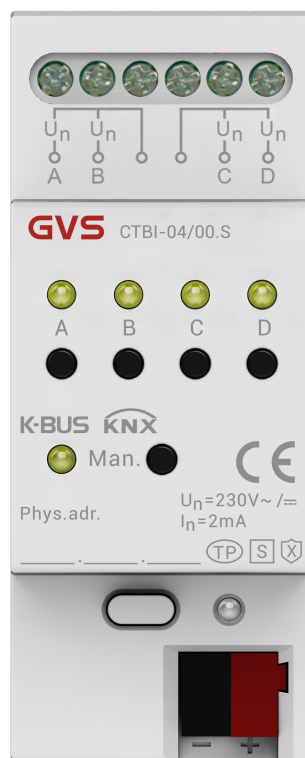


User Manual

K-BUS Binary Inputs with Secure, 4-Fold_V1.0

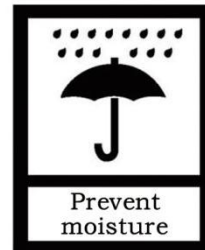
CTBI-04/00.S



KNX/EIB Home and Building Control System

Attentions

1. Please keep devices away from strong magnetic field, high temperature, wet environment;



2. Do not fall the device to the ground or make them get hard impact;



3. Do not use wet cloth or volatile reagent to wipe the device;



4. Do not disassemble the devices.

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Chapter 1 General

The Binary input with Secure, 4-Fold fulfills the individual demands in functional buildings as well as in residential buildings. In the same way, system planners are provided with varied application possibilities with regard to the implementation of functions. The Binary input with Secure, 4-Fold can install to be system with KNX bus and other device, and the functions are both simple to operation and intuitive. Users can program it according to the requirement to implement the function systematically.

This manual provides detailed technical information about the Binary input with Secure, 4-Fold for users as well as assembly and programming details, and explains how to use the binary input by the application examples.

1.1. Product and functional overview

The Binary input with Secure, 4-Fold is a modular installation device for fast installation in the distribution board on 35 mm mounting rails to DIN EN 60 715. The electrical connection is implemented using screw terminals. The connection to the bus is implemented using the supplied bus connection terminal. The binary input is connected to the input directly instead of an extra voltage supply. It is available to assign the physical address and configure the parameters by engineering design tools ETS with .knxprod (support edition ETS5.7 or higher).

The devices feature one manual operation button and one LED per channel. The inputs can be operated manually with this button, and the LED indicates contact connection state. In the case of manual operation, there is no additional voltage input.

The Binary input with Secure, 4-Fold serve as interfaces for operation of KNX systems via conventional buttons/switches or for coupling of binary signals (signal contacts, such as input 24V~230V).

The Binary input with Secure, 4-Fold has many functions that can be used in a wide variety of application areas. The following list provides an overview:

- **Switch and dimming function. (also 1 button operation)**
- **Control of blinds and shutters. (also 1 button operation)**
- **Sending of values e.g. temperature values, time etc.**

- **Control and storing of light scenes.**
- **Operation of various loads by multiple push button actions.**
- **Operation of several loads in a fixed switching sequence.**
- **Standard counting and differential counting**
- **Channel disable/enable function**
- **Support the KNX Data Secure**

Each input can take over any of the functions described above. Buttons on the front of the device can be used to simulate the input state. The status of the inputs are displayed by LEDs.

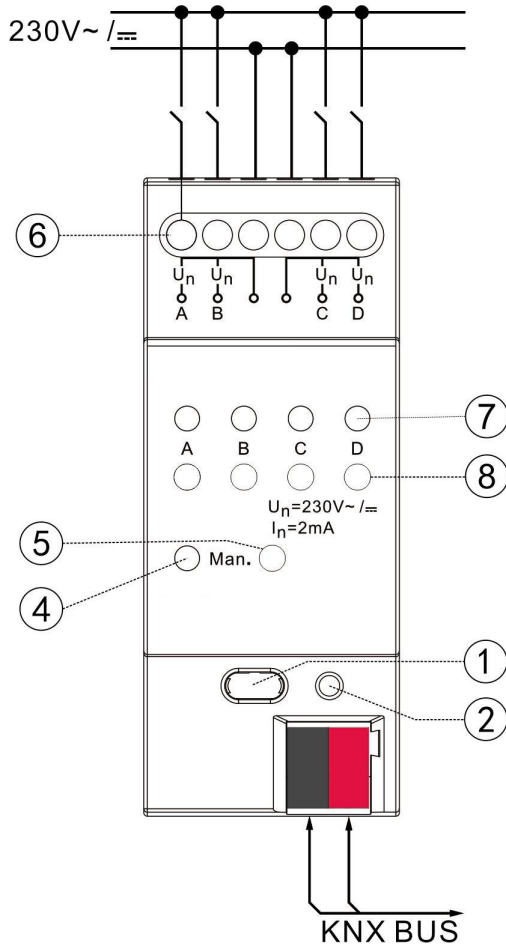
Chapter 2 Technical data

Power supply	Bus voltage	21-30V DC, via the KNX bus
	Bus current	<6.0mA/24V; 5.5mA/30V
	Bus consumption	<165mW
Input	Number	4
	Permitted voltage range U_n	0.....265V AC/DC
	Input current I_n	Max.2mA
	Signal level for 0-signal	0.....3V AC/DC
	Signal level for 1-signal	9.....265V AC/DC
Connections	KNX	Via bus connection terminal
	Inputs	Using screw terminals
	Cable cross-section	Multi core 0.2.....2.5mm ² Single core 0.2.....4.0mm ²
	Tightening torque	Max.0.6 Nm
	Permitted cable length	≤100M (cross section for 1.5mm ²)
	Operating and display	Programming button and red LED
Green LED flashing		For display the application layer running normally
Channel LED		1LED per channel for display of the input state
Manual operation button		1 button per channel for changing the input
Manual/Automatic LED		State 1LED for display of the manual/automatic mode states
Manual/Automatic button	1 button for switchover of manual and automatic mode	
Temperature	Operation	-5 °C ... 45 °C
	Storage	- 25 °C ... 55 °C

	Transport	- 25 °C ... 70 °C
Design	Modular installation device	Modular installation device, ProM
	Dimensions	90×36×64mm (H×W×D)
Installation	On 35mm mounting rails	
Weight	0.1KG	
Housing/color	Plastic housing, beige	

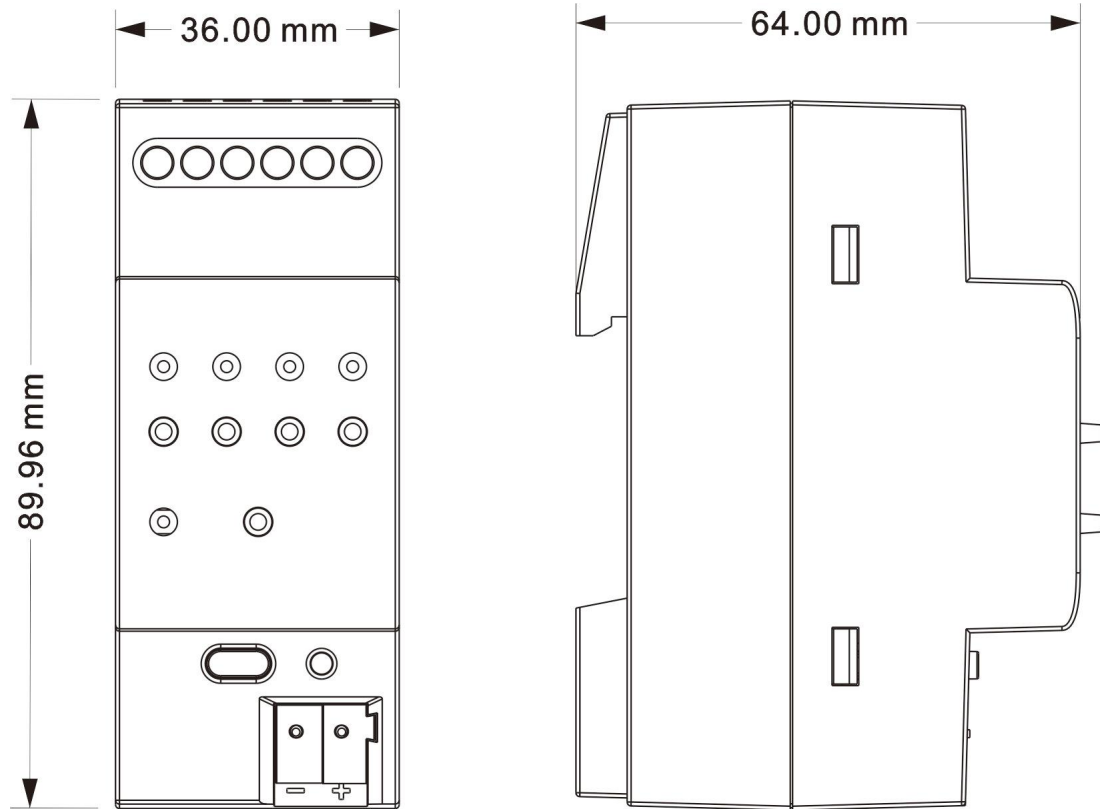
Chapter 3 Circuit and dimension diagram

3.1. Circuit diagram



- 1、 Programming button
- 2、 Programming LED
- 3、 Bus connection terminal
- 4、 Manual/automatic LED
- 5、 Manual/automatic button
- 6、 Connection terminals
- 7、 Channel LED
- 8、 Manual operation button

Reset the device to the factory configuration: press the programming button and hold for 4 seconds then release, repeat the operation for 4 times, and the interval between each operation is less than 3 seconds.

3.2. Dimension diagram

Chapter 4 Project design and programming

4.1. Overview of the functions

Application program	Max. number of communication objects	Max. number of group address	Max. number of associations	Secure group addresses
Binary Inputs with Secure, 4-Fold/00E8 2.0	35	60	60	60

The following operating modes are available for each channel.

■ Switch function / fault signal input

The function is used for switching the lighting or scanning conventional contacts, such as dimmer and switch actuator. Distinction between long and short operation and cyclical sending of the contact state are possible.

■ Switch/dimming function

For switching/dimming the lighting via a one push button or two push buttons function. Start-stop dimming and stepwise dimming as well as dimming via a single push button is possible.

■ Value/force output

It is possible to send different values or data types (e.g. temperature values, time or scene.) after a short/long operation. The activation/deactivation of the priority control of actuators is also possible. No distinction between long and short operation, sending different values or data types on rising/falling edge.

■ Scene control

The function is used for recalling and storing the states of several actuator groups. The actuator groups can be controlled via max. 6 individual objects.

■ Switching sequence

The function is used for the operation of several actuator groups in preset sequences, e.g. the latching relay. It is also used for operation of several loads in a fixed switching sequence.

■ Counter

This is used for counting input pulses. Different data types can be set for the counter. It is also able

to set the counting rate, and whether to sending the current counting values cyclically to the bus. When enable the differential counter, the differential counter can reset the count value and report in count overflow. Count can be stopped in overflow. Thereby, it is convenient to count the daily consumption.

■ **Push button with multiple operation**

For triggering various functions depending on the frequency of the operation. A long operation can also be detected and trigger a function.

■ **Shutter control**

For movement/lamella adjustment of a blind or a shutter via a one push button or two push buttons function. Eight preset operating responses are possible in total.

■ **Channel disable/enable function**

Each channel of a device can be disabled separately via a communication object.

Chapter 5 Parameter setting description in the ETS

5.1. KNX Secure

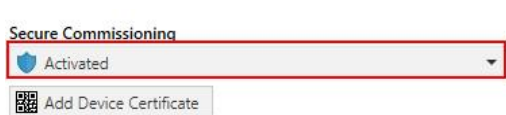
Binary Inputs with Secure, 4-Fold is a KNX device that complies with the KNX secure standard. That is, you can run the device in safe way.



Fig.5.1 (1) "KNX Secure" parameter window

The device with KNX secure will be displayed notes on ETS, as shown as Fig.5.1(1).

If secure commissioning is activated in ETS project, the following information must be considered during device debugging:



❖ It is essential to assign a project password as soon as a KNX Secure device is imported into a project. This will protect the project against unauthorized access.

The password must be kept in a safe place – access to the project is not possible without it (not even the KNX Association or device manufacturer will be able to access it)!

Without the project password, the commissioning key will not be able to be imported.

❖ A commissioning key is required when commissioning a KNX Secure device (first download). This key (FDSK = Factory Default Setup Key) is included on a sticker on the side of the device, and it must be imported into the ETS prior to the first download:

❖ On the first download of the device, a window pops up in the ETS to prompt the user to enter the key, as shown in Fig.5.1 (2) below.

The certificate can also be read from the device using a QR scanner (recommended).

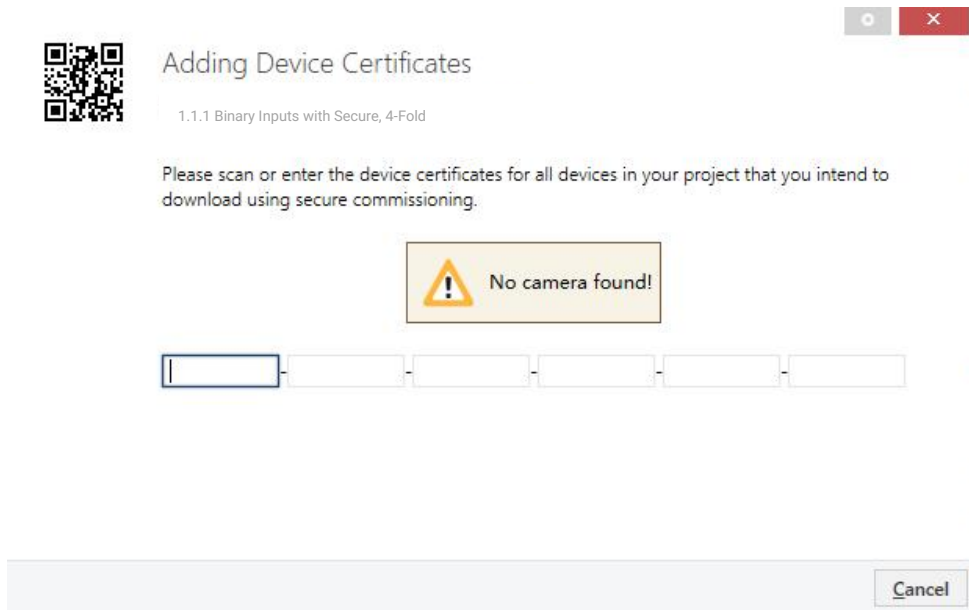


Fig.5.1(2) Add Device Certificate window

✧ Alternatively, the certificates of all Secure devices can be entered in the ETS beforehand.

This is done on the "Security" tab on the project overview page, as shown in Fig.5.1(3) below.

The certificates can be also added to the selected device in the project, as shown in Fig.5.1(4).

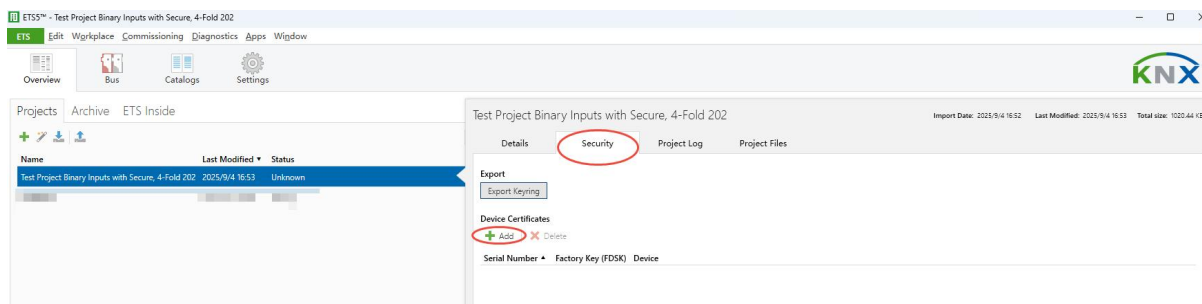


Fig.5.1(3) Add Device Certificate

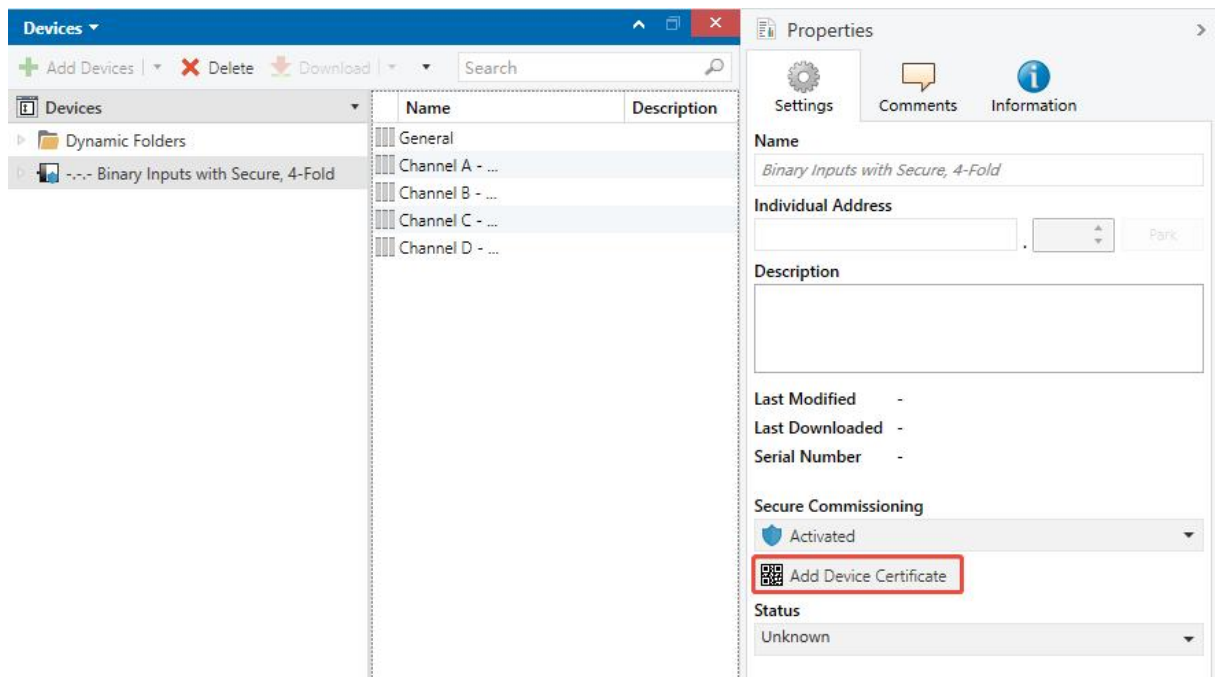


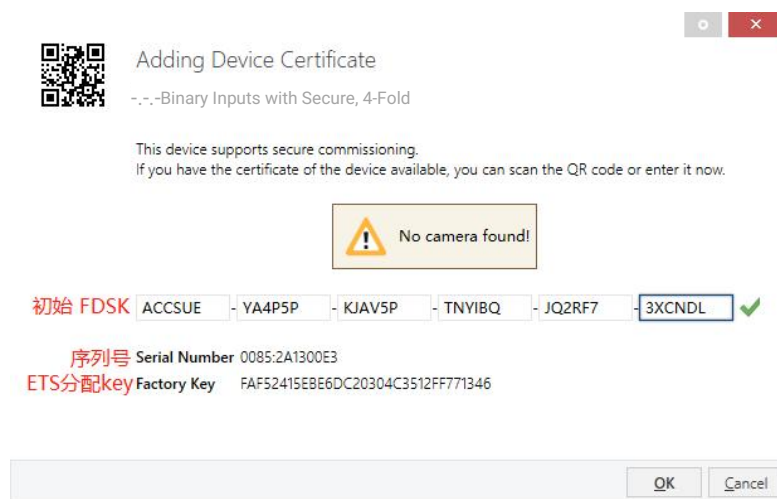
Fig.5.1(4) Add Device Certificate

✧ There is a FDSK sticker on the device, which is used for viewing FDSK number.

Without the FDSK, it will no longer be possible to operate the device in KNX Secure mode after a reset.

The FDSK is required only for initial commissioning. After entering the initial FDSK, the ETS will assign a new key, as shown in Fig.5.1(5) below.

The FDSK will be required again only if the device was reset to its factory settings (e.g. If the device is to be used in a different ETS project).



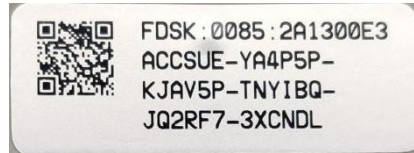


Fig.5.1(5)

Example:

If this application in the project needs to be tried with another device, it is no longer the original device. When the application is downloaded to a new device, the following prompt will appear on the left of Fig.5.1(6), click yes, the Add Device Certificate window will appear, then enter the initial FDSK of the new device, and you need to reset the device to the factory settings (it is not required if the device is still factory default; If it has been used, it will be required to reset, otherwise the following error message will appear on the right of Fig.5.1(6)), and then the device can be successfully downloaded again.

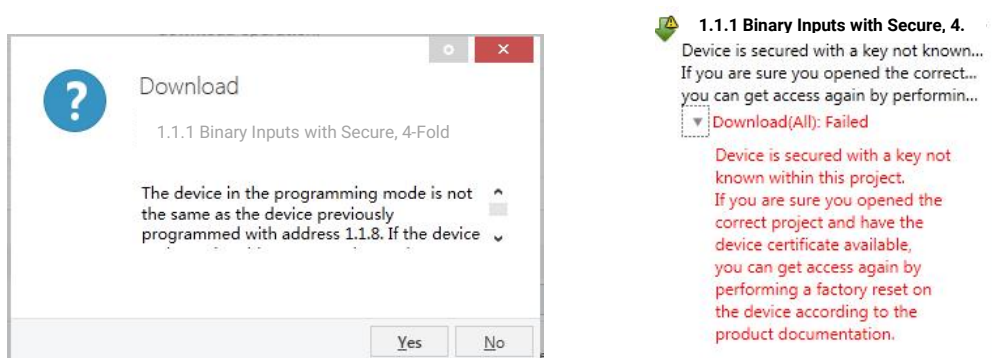


Fig.5.1(6) Example

Whether the device is replaced in the same project, or the device is replaced in a different project, the processing is similar: **Reset the device to the factory settings, then reassign the FDSK.**

After the device is downloaded successfully, the label Add Device Certificate turns gray, indicating that the key for this device has been assigned successfully, as shown in Fig.5.1(7) below.

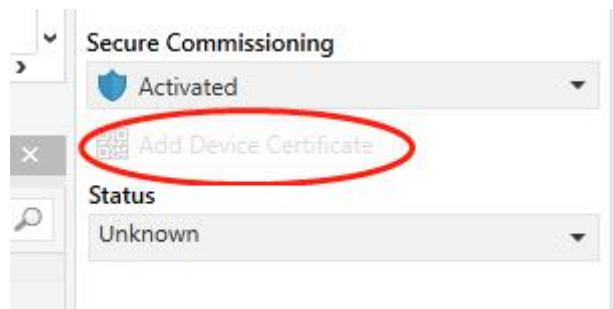


Fig.5.1(7)

ETS generates and manages keys:

Keys and passwords can be exported as needed to the use of security keys outside of the associated ETS projects. As shown in Fig.5.1(8) below, the file extension is .knxkeys.

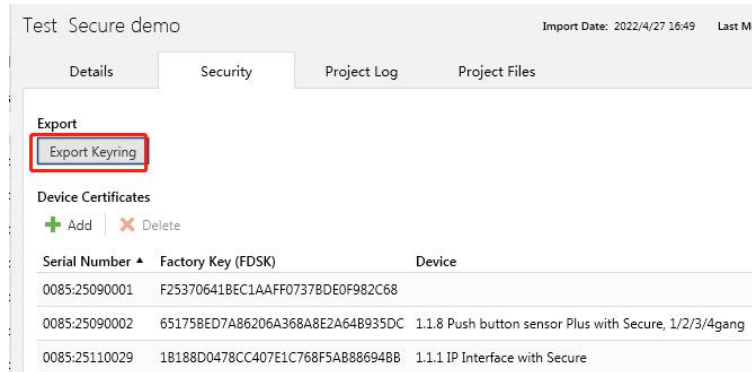


Fig.5.1(8)

Note: Any USB interface used for programming a KNX Secure device must support "long frames".

Otherwise ETS will report a download failure information, as shown below.

5.2. Parameter window "General Setting"

Parameter window "General Setting" can be shown in fig. 5.2. The function is used for limiting the number of sending telegrams to the bus, which can affect the complete device. The device initialization takes about 5s. It is possible to switch between manual operation and automatic operation by pressing the manual/automatic button about 2s. When the manual/automatic operations are switched successfully, the manual/automatic LED will flash for three times. In the manual mode the manual/automatic LED is on. In the automatic mode the manual/automatic LED is off. The devices are in automatic mode after connection to the bus, and the respective manual operation buttons do not have a function.

Send cycle of "In operation" telegram [1..240,0=inactive]	<input type="text" value="0"/>	s
Limit number of Tele.	<input checked="" type="checkbox"/>	
Period	<input type="text" value="500ms"/>	
Max. number tele. within a period [1..255]	<input type="text" value="20"/>	
Manual operation	<input type="radio"/> Enable/Disable via object <input checked="" type="radio"/> Enable	
Manual to automatic by	<input checked="" type="radio"/> Both push button and automatic delay time <input type="radio"/> Only push button	
Delay time [10..60000]	<input type="text" value="100"/>	s
Send Man./Auto. Status when the result change	<input checked="" type="checkbox"/>	

Fig.5.2 Parameter window "General Setting"

Parameter "Send cycle of In operation telegram [1..240,0=inactive]s"

This parameter is for setting the time interval when this device cycle send telegrams through the bus to indicate this module in normal operation. When set to "0", the object "in operation" will not send a telegram. If the setting is not "0", the object "In operation" will send a telegram according to the set period time with logic "1" to the bus. Options: **0...240s, 0= inactive**

As to reduce the bus load as much as possible, the maximum time interval should be selected according to actual needs.

Parameter "Limit number of Tele."

It is used to set whether limit the number of sending telegrams to decrease the burthen on the bus. It is possible to set how many telegrams can be sent within an adjustment period.

When enabled, the "Period" and "Max. Number Tele. within a period" parameters appear.

Parameter "Period"

The limit time of sending telegrams is set with the parameter. Options :

300ms

500ms

.....

10min

When device completes initialization in bus voltage recovery, start the observation period, and start count the sent telegrams. As soon as the Max. Number of transmitted telegrams has been reached, no further telegrams are sent on the bus until the end of the observation period. With the start of a new observation period, the telegram counter is reset to zero and the sending of telegrams is permitted again.

Parameter "Max. Number Tele. Within a period"

This parameter sets the number of telegrams which can be sent within an observation period.

Options: **1...255**

Parameter "Manual opeation"

The parameter defines if the switchover between the "manual operation" and "automatic operation" operating states is disabled or enabled using the manual/automatic button on the binary input. Options :

Enable/Disable by object

Enable

If the "enable/disable by object" is selected, the "Man. /Auto" communication object appears. The object receiving telegram value "0" disable the manual/automatic button, and then the manual / automatic mode cannot be switched. If the object receiving telegram value "1" enable the manual/automatic button, and then the manual/automatic mode can be switched.

If the "enable" is selected, the manual/automatic button has been enabled.

Parameter "Manual to automatic by"

This parameter defines how long the binary input remains in the "manual operation" state after the "manual/automatic button" has been pressed. Options:

Both push button and automatic delay time

Only push button

If the "only push button" option is selected, the binary input will remain in "manual operation" until the manual/automatic button is pressed again.

If the "Both push button and automatic delay time" option is selected, the binary input will remain in "manual operation" until the manual/automatic button is pressed again or the parameterized Manual to automatic after $[10...60000]*1s$ has timed out.

Parameter "Delay time $[10...60000]*1s$ "

The parameter appears when Both push button and automatic delay time is selected in the parameter manual to automatic by. It is used for setting the time for automatic reset from the "manual operation" to "automatic operation" state after the last push of a button. Option: **10.....60000s**

Parameter "Send Man./Auto. Status when the result change"

The parameter defines whether report on man/auto status change, and the current status can be sent to the bus. Options:

Yes

No

When enabled, the "Man/Auto., Status" communication object appears. The object sends telegram value "1", the current status for manual operation; the object sends telegram value "0", the current status for automatic operation. When operation status changed, the object sends the current status telegram on the bus immediately.

5.3. Parameter window “Channel Setting”

Parameter window “Channel Setting” can be shown in fig. 5.3, it used to set the work mode for channels, whether the respective manual operation buttons do have a function in the manual mode and set the channel LED indicate as a normal or inverted function for binary input in manual or automatic mode.

Channel A&B use as	<input checked="" type="radio"/> Individual channel	<input type="radio"/> Rocker channel
Channel C&D use as	<input checked="" type="radio"/> Individual channel	<input type="radio"/> Rocker channel
<hr/>		
Channel A Manual Button	<input checked="" type="checkbox"/>	
Channel B Manual Button	<input checked="" type="checkbox"/>	
Channel C Manual Button	<input checked="" type="checkbox"/>	
Channel D Manual Button	<input checked="" type="checkbox"/>	
<hr/>		
LED indicate of Channel A	<input checked="" type="radio"/> Normal	<input type="radio"/> Inverted
LED indicate of Channel B	<input checked="" type="radio"/> Normal	<input type="radio"/> Inverted
LED indicate of Channel C	<input checked="" type="radio"/> Normal	<input type="radio"/> Inverted
LED indicate of Channel D	<input checked="" type="radio"/> Normal	<input type="radio"/> Inverted

Fig.5.3 Parameter window “Channel Setting”

Parameter “Channel A&B use as”
 Parameter “Channel C&D use as”

This parameter is used to set the work mode for channels. Detail description in chapter [5.4](#).

Options:

Individual channel

Rocker channel

Parameter “Channel A.. D Manual button”

This parameter enables or disables the operation of the manual operation button. It is set separately for each channel. Options:

Enable

Disable

If the "Enable" option is selected, the manual operation button is enabled. The first time the manual operation button is actuated, closing of the "external contact" is simulated, nothing happens when the button is released. The second time the manual operation button is actuated, opening of the "external contact" is simulated, nothing happens when the button is released.

If the "Disable" option is selected, the manual operation button is disabled, and the manual operation buttons do not have a function. On disabled channels the respective channel LED will not react if the respective manual operation button is pressed.

For safety-relevant systems such as for fault signals the button functions are inhibited using the disable option.

Parameter "LED indicate of Channel A/B/C/D"

This parameter is used to represent the LED display as a normal or inverted function. It is set separately for each channel. Options:

Normal

Inverted

If the "Normal" option is selected, represent the LED display as a normal function, then contact is closed(signal is present), LED is on; Contact is open (no signal), LED is off.

If the "inverted" option is selected, represent the LED display as a inverted function, then contact is closed(signal is present), LED is off; Contact is open (no signal), LED is on.

5.4. Parameter window “Channel A~D”

Parameter window “Channel A~D” can be shown in fig. 5.4. Channel function of Binary input can select two ways of working. If the “Individual channel” working way is selected, each channel can be set individual. If the “Rocker channel” working way is selected, two channels can be set to work rocker, such as channel A and channel B rocker, channel C and channel D rocker. Each individual channel can be set individual, which is used to set dimming and shutter functions. It is able to switch and dimming together with one button operation input, and it is also able to move and stop shutter with one button operation. Detail description in chapter [5.4.1](#) and chapter [5.4.2](#).

Function of the channel	<input type="text" value="No Function"/>
Description (max 30char.)	<input type="text"/>

Fig.5.4 (1) Parameter window “Channel A~D” (Individual)

Function of Channel A&B	<input checked="" type="radio"/> Dimming <input type="radio"/> Shutter
Description (max 30char.)	<input type="text"/>
Channel assignment for Channel A/B	<input type="text" value="Off,darker / On,brighter"/>
Connect contact type	<input type="radio"/> Normally open <input checked="" type="radio"/> Normally closed
Debounce Time	<input type="text" value="10"/> ms

Fig.5.4(2)Parameter window “Channel A~D” (Rocker)

5.4.1. Rocker channel

In the rocker working mode for binary input, each rocker channel can be set separately, and parameters and objects which are assigned to each rocker channel are the same. Using rocker channel A/B as an example described, the parameters can be shown in fig.5.4(2).

Parameter "Function of Channel X&Y (X=A/C, Y=B/D) "

The parameter set the functions of channel X/Y in the rocker, which is used to set dimming or shutter. Options:

Dimming

Shutter

The rocker function of channel X/Y can realize the dimming or the shutter via two objects. In automatic operation mode, channels input for 9~265V. In manual operation mode, channels input by manual operation buttons.

Parameter "Description (max 30char.)"

This parameter is for setting the name description of channel, up to input 30 characters.

Parameter "Channel assignment for Channel X/Y (X=A/C, Y=B/D) "

The parameter set the function assignment of channel X/Y in the rocker function for dimming.

Options:

Off, darker / on, brighter

On, brighter / off, darker

Toggle, darker / Toggle, brighter

Toggle, darker / Toggle, brighter

If the "Off, darker / On, brighter" option is selected, represent input signal for "off, darker" when contact of channel X is closed, input signal for "stop darker" when contact of channel X is open. However, channel Y is opposite, Input signal for "on, brighter" when contact of channel Y is closed, input signal for "stop bright" when contact of channel Y is open.

In the function assignment of channel X/Y other options are similar with the above option. The on/off formation is sent to the bus via the object "switch, the darker/brighter formation is sent to the bus via the object "dimming".

Here setting the function assignment of channel X/Y in the jointly function for shutter. Options:

MOVE Up/MOVE Down with stop

MOVE Down/MOVE Up with stop

If the "MOVE Down/MOVE Up with stop" option is selected, the shutter move down when contact of channel X is closed, the shutter move up when contact of channel Y is closed. When the contact of channel X/Y is open, the shutter stops moving down/up.

Another option is similar with the above option. The shutter moves up/down via the object "Up/Down". To stop shutter moving via the object "Stop".

Parameter "Connect contact type X/Y"

The parameter defines whether the input contact is a normally closed or normally open contact when actuated for channels x/y. Options:

Normally closed

Normally open

The parameters that are described in this chapter are based on normally open connect type as example, the normally close connect type is just opposite.

Parameter "Debounce Time X/Y"

This parameter is used to set the debounce time for channel X/Y. Debouncing prevents unwanted multiple operation of the input, e.g. due to bouncing of the contact. Options:

10ms

20ms

.....

150ms

5.4.2. Individual channel

In the individual working mode for binary input, each channel can be set separately, and parameters and objects which are assigned to each channel are the same. Using channel A as an example described.



Function of the channel: No Function

Description (max 30char.):

Fig.5.4.2 Parameter window "Channel X"

Parameter "Function of the Channel"

The parameter is set function of the channel. Options:

- No function**
- Switch**
- Switch/Dimming**
- Value / Forced output**
- Scene Control**
- Switching sequence**
- Counter**
- Multiple operation**
- Shutter control**

Each operating mode is assigned to the corresponding parameters and objects, the follow chapters in detail.

Parameter "Description (max 30char.)"

This parameter is for setting the name description of channel, up to input 30 characters.

5.4.2.1. Switch

Parameter window "Switch" can be shown in Fig.5.4.2.1(1) and Fig5.4.2.1(3). It is visible when Function of the channel "Switch" is selected. No distinguish between long and short operation in Fig.5.4.2.1(1). It is opposite in Fig. 5.4.2.1(3).

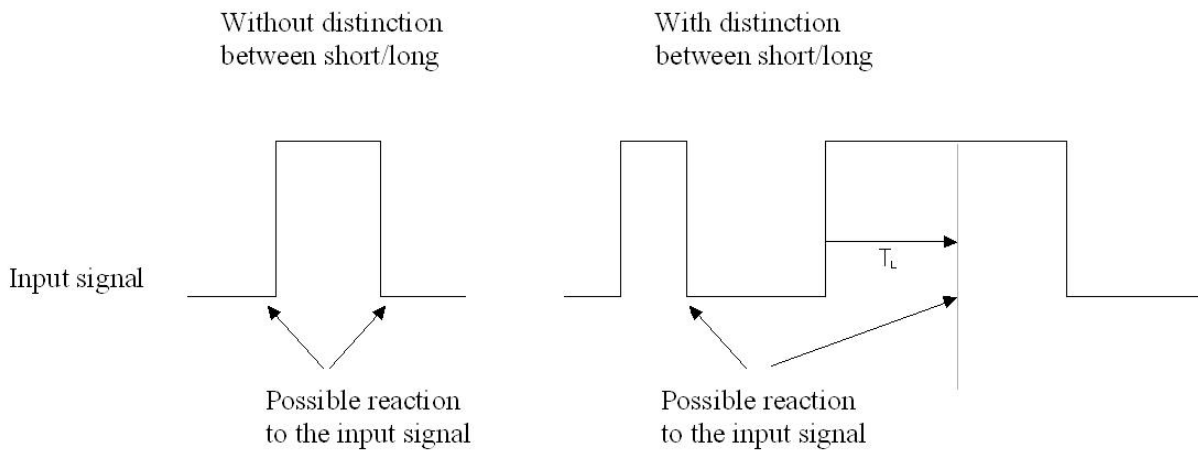
Function of the channel	Switch
Description (max 30char.)	<input type="text"/>
Distinction between long and short operation	<input type="checkbox"/>
Cyclic send Tele."Tele.switch"	Always
Reaction on close the contact	TOGGLE
Reaction on open the contact	No action
Interval of tele.cyclic send: Base	1s
Factor[1..255]	10
Send object value after voltage recovery(if YES not equal TOGGLE)	<input checked="" type="checkbox"/>
Debounce time/Min Time	50 ms

Fig.5.4.2.1(1) Parameter window "Switch" (No distinction long/short operation)

Parameter "Distinction between long and short operation"

This parameter defines whether the input distinguishes between a short and long operation. If "Yes" is selected, there is a delay after opening/closing the contact to determine whether there is a short or long operation. Only then is a possible reaction triggered.

The following diagram illustrates the function.



Options:

Yes

No

Note : The long operation in the below chapters are the same with here. T_L is the period after which a push button action is recognized as a long operation.

Parameter "Cyclical send Tele. "Tele. Switch"

This parameter is visible if there is no distinction between a short and long operation. It is able to set whether to send the current value of object "Switch" cyclically on the bus. Options :

No

If switch off

If switch on

Always

If the parameter value "if switch off" or "if switch on" is set, only the corresponding object value is sent cyclically.

If the parameter value "always" is selected, the object sends cyclically on the bus, regardless of its value is 0 or 1.

Parameter "Reaction on closing the contact "

Parameter "Reaction on opening the contact"

This parameter is visible if there is no distinction between a short and long operation. There is set the reaction on closing or opening the contact. Options :

No action

Off

On

Toggle

Stop cyclic send

If "Toggle" is selected, the current operation is inverted in next operation. For example, if the current operation is "On", the next operation will become "off".

If "Stop cyclic send" is selected, it will stop the cyclical sending telegram till there is a new object value to be sent. If "No action" is selected, it will not implement any operation.

Parameter "Interval of Tele. cyclic send: Base × Factor"

This parameter is used to set the interval time between two telegrams that are sent cyclically, it is visible if cyclical sending has been set. Transmission cycle time = Base × Factor.

Base options: **0.5s/1s/ .../1h**

Factor options: **1...255**

Parameter "Send object value after voltage recovery (if yes not equal toggle)"

It can be set whether to send the value of the object "Tele. Switch" on the bus after bus voltage recovery, this parameter is visible if there is no distinction between a short and long operation.

When enabled, a value is however only sent on the bus if the value "toggle" has not been set in either of the two parameters "Reaction on closing the contact/ opening the contact". If one of the two parameters has the value "toggle", no values are sent in general on the bus after bus voltage recovery. If "No reaction" or "Stop cyclic send" is selected, there is no values are sent on the bus either.

Parameter "Debounce time/Min Time"

This parameter is used to set the debounce time. Debouncing prevents unwanted multiple operation of the input, e.g. due to bouncing of the contact.

Options: **10ms/20ms/...../150ms/Min. operation**

The "Min. operation" time can only be set when there is no distinction between a short and a long operation. This option is different from others, the Minimum time of the contact operation is not only means the effective time when contact close, but also the contact open. The parameter window can be

shown in Fig. 5.4.2.1(2):

Function of the channel	Switch
Description (max 30char.)	
Distinction between long and short operation	<input type="checkbox"/>
Cyclic send Tele."Tele.switch"	Always
Reaction on close the contact	TOGGLE
Reaction on open the contact	No action
Interval of tele.cyclic send: Base	1s
Factor[1..255]	10
Send object value after voltage recovery(if YES not equal TOGGLE)	<input checked="" type="checkbox"/>
Debounce time/Min Time	Min. operation ms
Minimum operation time: Base	1s
Factor [1..255]	10

Fig 5.4.2.1(2) Parameter window "Mini Time"

Parameter "Minimum operation time : Base×Factor"

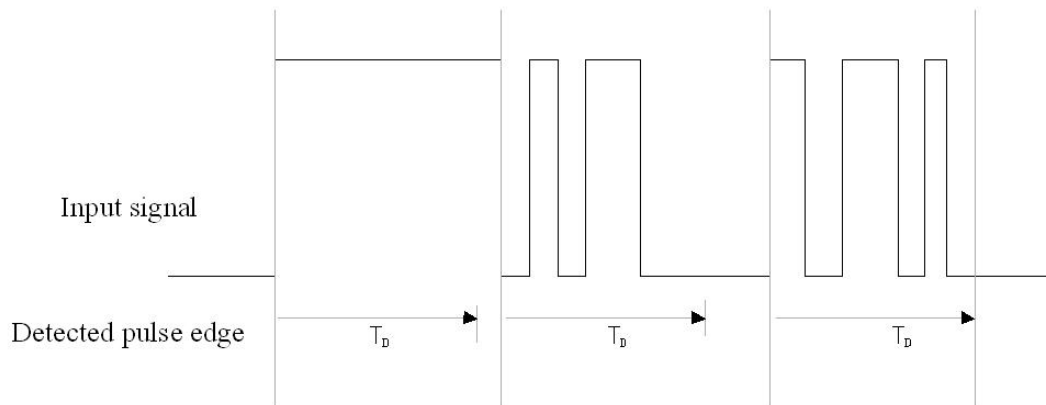
The minimum time of the contact operation is: $Base \times Factor$

Base options: **100ms//1h**

Factor options: **1~255**

Note : The parameter window "Debounce time/Min Time" and the explanation of option "Min. operation" are the same with here in the below chapters.

To prevent the debounce process: If a pulse edge is detected at the input, the input reacts to it immediately (e.g. by sending a telegram). The debounce time T_D starts simultaneously. The signal at the input is not evaluated within the debounce period. As shown below:



Once a pulse edge has been detected at the input, further edges are ignored for the duration of the debounce time T_D .

The process of preventing debounce in the below chapters are the same with here. T_D is the effective time of a pulse edge input, namely the period after a input signal is recognized as a operation.

Function of the channel	Switch
Description (max 30char.)	<input type="text"/>
Distinction between long and short operation	<input checked="" type="checkbox"/>
Connect contact type	<input type="radio"/> Normally open <input checked="" type="radio"/> Normally closed
Reaction on short operation	TOGGLE
Reaction on long operation	No action
Long operation after: Base	1s
Factor[2..255]	10
Number of objects for short/long object operation	1
Debounce time	50 ms

Fig.5.4.2.1(3) Parameter window "Switch" (Distinction long/short operation)

Parameter "Connected contact type"

This parameter is visible if there is distinction between a short and long operation. It is used to set whether the input contact is a normally closed or normally open contact. Options:

Normally open

Normally closed

The parameters that are described in this chapter are based on normally open connect type as example, the normally close connect type is just opposite.

Parameter "Reaction on short operation"

Parameter "Reaction on long operation"

The parameter is visible if the option yes has been selected with the parameter distinction between long and short operation. It is used to set if the object value is ON, OFF, TOGGLE, or if no action should be occur. The object value is updated as soon as it has been determined if a short or long operation has occurred. Options:

No action

Off

On

Toggle

Parameter "Long operation after: base×Factor"

The parameter is visible if the option yes has been selected with the parameter distinction between long and short operation. Here defines the period T_L after which an operation is interpreted as "long".

$$T_L = \text{Base} \times \text{Factor}$$

Base options: **100ms/1s/..... /1h**

Factor options: **2~255**

Parameter "Number of objects for short/long object operation"

The parameter is visible if the option yes has been selected with the parameter distinction between long and short operation. It is able to set one or two communication objects for short/long operation. When one communication object is set, long and short operations share a communication object. When two communication objects are set, long and short operations use a communication object separately.

Options:

1

2

5.4.2.2. Switch/Dimming

Parameter window "Switch/Dimming" can be shown in Fig.5.4.2.2. It is visible when function of the channel "Switch/Dimming" is selected. It is possible that switch and dimming the lighting via a button operation.

Function of the channel	Switch/Dimming
Description (max 30char.)	
Connect contact type	<input type="radio"/> Normally open <input checked="" type="radio"/> Normally closed
Dimming functionality	<input checked="" type="radio"/> Dimming and switching <input type="radio"/> Only dimming
Reaction on short operation	TOGGLE
Reaction on long operation	Dim brighter/darker with start brighter
Long operation after	1 s
Debounce time	50 ms
Dimming mode	<input type="radio"/> Start-stop dimming <input checked="" type="radio"/> Step dimming
Step size	1.56 %
Interval of tele.cyclic send	1 s

Fig.5.4.2.2 Parameter window "Switch / Dimming"

Parameter "Connect contact type"

This parameter defines whether the input contact is a normally closed or normally open contact. Options:

Normally open

Normally closed

The parameters that are described in this chapter are based on normally open connect type as example, the normally close connect type is just opposite.

Parameter "Dimming functionality"

This parameter is used to define whether the lighting can only be dimmed or whether it also should be permitted switching. In this case a long operation actuated dimming and a short operation actuates switching. Options:

Dimming and switching

Only dimming

If “Only dimming” is selected, there is no distinction between a short and long operation. Therefore the dimming is carried out immediately after an operation action; there is not required to determine whether the operation is long or short.

If “Dimming and switching” is selected, it will distinguish the operation is a short or long operation. In this case, the lighting is dimmed via a long operation and switched via a short operation.

Parameter “Reaction on short operation”

The parameter is visible if the option dimming and switching has been selected with the parameter dimming functionality. It is used to set if the value of object “Switch” is On, Off, Toggle, or if No action should be occur with short operation. Options:

No action

Off

On

Toggle

Parameter “Reaction on long operation”

The parameter is visible if the option “dimming and switching” has been selected with the parameter “dimming functionality”. It is used to set if the object “Dimming” sends a brighter or darker telegram with long operation. When the operation is over, the object will send a stop dimming telegram. Options:

Dimming brighter

Dimming darker

Dim brighter / darker with start brighter

Dim brighter / darker with start darker

If the option “Dim brighter / darker with start darker” is selected, the dim command which is the opposite to the last dim command is set, and the first action is dimming darker with long operation. Other options are similar with the option.

Parameter “Long operation after”

The parameter is visible if the option “dimming and switching” has been selected with the

parameter "dimming functionality". Here defines the period T_L after which an operation is interpreted as "long".

Options: **0.3s/0.5s/...../10s**

Parameter "Reaction on operation"

The parameter is visible if the option "only dimming" has been selected with the parameter "dimming functionality". There is no distinction between short and long operation. Therefore the object "dimming" will send a brighter or darker telegram after an operation trigger. When the operation is over, the object will send a stop dimming telegram. Options:

Dimming brighter

Dimming darker

Dim brighter / darker with start brighter

Dim brighter / darker with start darker

Parameter "Debounce time/Min Time"

This parameter is used to set the debounce time. Debouncing prevents unwanted multiple operation of the input, e.g. due to bouncing of the contact.

Options: **10ms/20ms/...../150ms/Min. operation**

The "Min. operation" can be set in fig.5.8 if the option only dimming has been selected with the parameter dimming functionality.

Parameter "Dimming mode"

The parameter sets whether the dimming mode is start-stop dimming or steps dimming. Options:

Start-stop dimming

Steps dimming

If the option "start-stop dimming" is selected, it will start the dimming mode with a bright or darker telegram and end the dimming mode with a stop dimming telegram at the end of operation. The dimming telegram need not be cyclically sent in start-stop dimming mode.

If the option "step dimming" is selected, the dimming telegram is sent cyclically during a long operation. The stop telegram ends the dimming process at the end of operation.

Parameter "Step size"

The parameter is visible if the option "step dimming" has been selected with the parameter "dimming mode". It is used to set the change brightness (in percent) which is cyclically sent with every dim telegram. Options:

100%

50%

.....

1.56%

Parameter "Interval of Tele. Cyclic send"

The parameter is visible if the option "step dimming" has been selected with the parameter "dimming mode". It is used to set the interval time between two telegrams that are sent cyclically during a long operation. Options:

0.3s

0.5s

.....

10s

5.4.2.3. Value/Forced output

Parameter window “Value/Forced output” can be shown in Fig. 5.4.2.3. It is visible when Function of the channel “Value/Forced output” is selected.

Function of the channel	Value/Forced output ▼
Description (max 30char.)	<input type="text"/>
Distinction between long and short operation	<input checked="" type="checkbox"/>
Connect contact type	<input checked="" type="radio"/> Normally open <input type="radio"/> Normally closed
Reaction on short operation	1 byte value [Recall Scene] ▼
8 bit recall scene	Scene No.1 ▼
Reaction on long operation	1 byte value [Recall Scene] ▼
8 bit recall scene	Scene No.1 ▼
Long operation after: Base	1s ▼
Factor [2..255]	10 ▲▼
Debounce time	50 ▼ ms

Fig.5.11(1) Parameter window “Value / Force output, X” (Distinction long/short operation)

Function of the channel	Value/Forced output ▼
Description (max 30char.)	<input type="text"/>
Distinction between long and short operation	<input type="checkbox"/>
Send object value after voltage recovery	<input checked="" type="checkbox"/>
Reaction on close the contact	1 byte value [Recall Scene] ▼
8 bit recall scene	Scene No.1 ▼
Reaction on open the contact	1 byte value [Recall Scene] ▼
8 bit recall scene	Scene No.1 ▼
Debounce time/Min Time	50 ▼ ms

Fig.5.11(2) Parameter window “Value / Force output, X” (No distinction long/short operation)

Parameter "Distinction between long and short operation"

This parameter defines whether the input distinguishes between a short and long operation. If "Yes" is selected, there is a delay after opening/closing the contact to determine whether there is a short or long operation. Only then is a possible reaction triggered. Options:

Yes

No

Parameter "Connect contact type"

This parameter is visible if there is distinction between a short and long operation. It is used to set whether the input contact is a normally closed or normally open contact. Options:

Normally open

Normally closed

The parameters that are described in this chapter are based on normally open connect type as example, the normally close connect type is just opposite.

Parameter "Reaction on short operation/close the contact" and "Reaction on long operation/open the contact"

If there is distinction between short and long operation, the parameter is used to define the data type that is sent when the contact is actuated with short or long operation. If no distinction, it defines the data type that is sent when the contact is actuated with close or open. Options:

the input pulse is generated with a opening contact (falling edge) and a closing contact (rising edge).

No reaction

1bit value [0/1]

.....

4 byte value [0...4294967295]

Parameter "Output value[...]"

Here defines the value which is sent with the operation. The value range depends on the data type set for the parameter "Reaction on short operation/close the contact" or "Reaction on long

operation/open the contact”

Parameter “Long operation after: Base × Factor [2..255]”

The parameter is visible if the option yes has been selected with the parameter distinction between long and short operation. Here defines the period T_L after which an operation is interpreted as “long”. $T_L = \text{Base} \times \text{Factor}$

Base options: **100ms/1s/...../1h**

Factor options: **2~255**

Parameter “Send object value after voltage recovery”

This parameter is visible if there is no distinction between a short and long operation as shown in fig. 5.4.2.3(2). It can be set whether to send the value of the object “close/open(....)” on the bus after bus voltage recovery.

When enabled, the object value will be sent on the bus after bus voltage recovery.

Parameter “Debounce time”

This parameter is used to set the debounce time. Debouncing prevents unwanted multiple operation of the input, e.g. due to bouncing of the contact. Options : **10ms/20ms/...../150ms/Min.**

operation

The “Min. operation” can be set in Fig.5.4.2.1(1). It can only be set when there is no distinction between a short and a long operation.

5.4.2.4. Scene control

Parameter window “Scene control” will be shown in Fig. 5.4.2.4, it will be visible when the function of the channel “Scene control” is selected. This function enables the states of several actuator groups to be recalled and stored.

Function of the channel	Scene control
Description (max 30char.)	
Connect contact type	<input type="radio"/> Normally open <input checked="" type="radio"/> Normally closed
Store Scene	On long operation
Long operation after	0.5 s
Debounce time	50 ms
<hr/>	
Control of actuator group A by	1 bit value [On/Off]
Preset value actuator group A [ON/OFF]	<input type="radio"/> Off <input checked="" type="radio"/> On
Store group A by object	<input checked="" type="checkbox"/>
Control of actuator group B by	1 bit value [On/Off]
Preset value actuator group B [ON/OFF]	<input type="radio"/> Off <input checked="" type="radio"/> On
Store group B by object	<input type="checkbox"/>

Fig.5.4.2.4 Parameter window “Scene control”

Parameter “Connect contact type”

This parameter is used to set whether the input contact is a normally closed or normally open contact. Options:

Normally open

Normally closed

The parameters that are described in this chapter are based on normally open connect type as example, the normally close connect type is just opposite.

Parameter “Store scene”

This parameter defines the manner in storing of the current scene.Options:

No

On long operation

With object value='1'
On long operation and object value='1'

The manner of storing scene in the following table provides an overview:

Parameter value	Behavior
On long operation	<p>As soon as a long operation is detected, the object "store scene" sends the value "1" on the bus and the objects "(...),group A...F" send read out telegram. If the object "store scene, X" have received a telegram "1", then the object value "1" will not send out again when long operation. The objects "(...),group A...F" can be modified via the bus for the duration of the long operation.</p> <p>Once the long operation has finished, the object "Store scene" sends the value "0" on the bus and the current object value can not be modified.</p> <p>On the long operation, If the object "Store scene" receives the value "0" on the bus, even the long operation has not finished, the current object value also can't be modified.</p>
If object value='1'	<p>If the object "Store scene, X" receives the value "1", the object values "(...),group A...F" are read out via the bus. Then the objects "(...),group A...F" can be modified via the bus.</p> <p>On receipt of the object value "0", the current object values can't be modified.</p>
On long operation and object value='1'	<p>If the object "Store scene" receives the value "1" on the bus, on the next long operation, the objects "(...),group A...E" send read out the telegram. The object values "(...),group A...E" can be modified via the bus for the duration of the long operation.</p> <p>If the object "Store scene" receives the value "0" on the bus, the current object value can't be modified; or the long operation has finished, the object "Store scene" sends the value "0" on the bus and the current object values also can't be modified.</p>

	<p>Provided that a "1" has not been received at the object "Store scene", a long operation is interpreted in the same way as a short operation, i.e. recall scenes.</p>
--	---

Parameter "Long operation after"

This parameter is visible when the parameter "Store scene" is "On long operation" or "On long operation and object value= '1'", it defines the period T_L here, after which an operation is interpreted as "long". Options: **0.3s/0.5s/...../10s**

Parameter "Debounce time"

This parameter is used to set the debounce time. Debouncing prevents unwanted multiple operation of the input, e.g. due to bouncing of the contact. Options: **10ms/20ms/...../150ms**

Parameter "Control of actuator group A...F by"

This parameter is able to set various data types for each of 6 actuator groups A...F. The actuator groups can be controlled via max. 6 individual objects. Data types of the object "Output 1bit/1byte/2byte, group A...F" depend on the data types which has been selected for the actuator groups. Options:

1bit value [ON/OFF]

1byte value[scale 0...100%]

1byte value[0...255]

2byte value [Temperature]

Parameter "Preset value actuator group A...F"

The parameter is used to set the preset value for each actuator group A...F. The value range depends on the data type set for the parameter "control of actuator group A...F by".

Parameter "Store group A...F by object"

It is used to set whether the preset value is allowed to be modified via the bus.

When enabled, the preset value can be modified via the object "Output 1bit/1byte/2byte, group A...F". If the bus voltage recovery this value will be modified as preset value. That is, the stored value is not saved.

5.4.2.5. Switching sequence

Parameter window “Switching sequence” can be shown in Fig. 5.4.2.5. It is visible if the function of the channel “Switching sequence” is selected. The switching sequence function enables up to five switch objects to be modified in a defined sequence by actuation of just a single input. Thus, up to reach five actuators or actuator groups can be switched in a defined sequence.

Function of the channel	Switching sequence ▾
Description (max 30char.)	<input type="text"/>
Connect contact type	<input type="radio"/> Normally open <input checked="" type="radio"/> Normally closed
No. of objects	3 level ▾
Type of swiching sequence	Sequentially on/off(several push buttons) ▾
Function on operation	<input checked="" type="radio"/> Switch upwards <input type="radio"/> Switch downwards
Sequence is: 000,001,011,111	<NOTE Information
Debounce time/Min Time	50 ▾ ms

Fig.5.4.2.5 Parameter window “Switching sequence”

Parameter “Connect contact type”

This parameter is used to set whether the input contact is a normally closed or normally open contact.Options:

- Normally open**
- Normally closed**

The parameters that are described in this chapter are based on normally open connect type as example, the normally closed connect type is just opposite.

Parameter “No .of objects”

The parameter set the number of communication objects has the same meaning the number of levels (max.5): The communication objects “level-1” to “level-5” are enabled accordingly. Options:

- 2level**
- 3level**
- 4level**
- 5level**

For example, parameter “3level” means there are 3 communication objects: “level-1”, “level-2”, and “level-3”. The first operation modified the value of “level-1”, the second operation modified the value of “level-2”, the third operation modified the value of “level-3”, the fourth from modified the value of “level-3”....., the switch sequence is: 000,001,011,111,011.....The data send on the bus is the value of the communication object that after modified, which is the alternative data.

The communication object “level increment/decrement, X” is used to increase or decrease the switch level, ‘1’ means increase 1 level and ‘0’ means decrease.

The follow table describes in detail (A 3 Level sequence as an example, the type is sequentially on/off (one push button)):

Switching sequence		Value of the communication objects		
Input operation number	Binary code	Level-3	Level-2	Level-1
0	000	Off	Off	Off
1	001	Off	Off	On
2 current operation	011	Off	On	On
3	111	On	On	On
4	011	Off	On	On
.....

In the above table, the current operation is 2; the next time will be to operation 3. But if the object “level increment/decrement, X” receive ‘1’(Increase a Level) the next time will jump one time forward ,and the next time will be to operation 4; also if the object “level increment / decrement, X” receive ‘0’(decrement a level) the next time will jump one time backward ,and the next time will be to position 2(no change).

In this function ,It only send the changed bit(This code value compare to the operation -1 value), for example from operation 2 to operation 3, The Most Significant Bit is changed, the object according to Level 3 will send value ‘1’.

Although the number of levels is different, their processes are similar in the case of the same switch sequence type.

Parameter "Type of switching sequence"

The switching sequence can be selected here. Each sequence has other object values for each switching level. Options:

Sequentially on/off (one push button)

Sequentially on/off (several push buttons)

All combinations

Take "3level" as the example to explain the difference between them (send the changed data on the bus, data "0"= OFF, "1"=ON):

Type of switching sequence	Example
Sequentially on/off (one push button)	...-000-001-011-111-011-001-...
Sequentially on/off (several push buttons)	000-001-011-111 or 111-011-001-000
All combinations	...-000-001-011-010-110-111-101-100-... (Gray code)

Parameter "Function on operation"

The parameter is only visible in the switching sequence "Sequentially on/off (several push buttons)". It can be set whether an operation of the push button switches up or down a level. Options:

Switch upwards

Switch downwards

The implement direction of the parameter "Switch upwards" is "000-001-011-111", the implement direction of the parameter "Switch downwards" is "111-011-001-000". After the bus voltage recovery, the current value is 000, if the parameter "Switch downwards" is selected, the effect will be invisible when operation, then it is possible to operation after switch up a few levels by the object "level increment/decrement".

Parameter "Sequence is..."

This parameter indicate the manage process of switching sequence.

Parameter "Debounce time/Min Time"

This parameter is used to set the debounce time. Debouncing prevents unwanted multiple operation of the input, e.g. due to bouncing of the contact. Options : **10ms/20ms/...../150ms/Min.**

operation

The "Min. operation" can be set in fig.5.4.2.1(1).

5.4.2.6. Counter

Parameter window “Counter” can be shown in Fig. 5.4.2.6. It is visible if the function of the channel “counter” is selected

Using the “Counter” function, the device is able to count the number of pulse edges at the input. A “differential counter” is therefore available if required in addition to the standard counter. Both counters are triggered by counting pulses but otherwise operate independently of each other. The data width which has been selected for both counters can be set to same or different.

The function of differential counter is similar with the main counter. The different is that the differential counter can reset the counter value (count from the initial value) and stop counting after overflow via the bus.

The parameters set as follows:

Function of the channel	Counter
Description (max 30char.)	
Debounce time/Min Time	50 ms
<hr/>	
Enable Differential Counter	<input checked="" type="checkbox"/>
Pulse detection on	Closing contact(rising edge)
Send object value after voltage recover	<input type="checkbox"/>
Cyclically send conter value Base:	100ms
Factor[1.255]:	10
<hr/>	
Main Counter	
Data width of counter	2byte [-32768..32767]
Send counter value on change	<input checked="" type="checkbox"/>
Send counter value cyclically	<input checked="" type="checkbox"/>
Counter limit value 1 [0]	0
Counter limit value 2 [-32768..32767]	0
Mode of counter	<input checked="" type="radio"/> Normal +1 <input type="radio"/> Manual set
<hr/>	
Differential Counter	
Data width of counter	2byte [-32768..32767]
When counter crossing limit value	<input checked="" type="radio"/> Continue circular counting <input type="radio"/> Stop until reset
Send counter value on change	<input checked="" type="checkbox"/>
Send counter value cyclically	<input checked="" type="checkbox"/>
Counter limit value 1 [-32768..32767]	0
Counter limit value 2 [-32768..32767]	1000
Mode of counter	Like main counter set

Fig.5.4.2.6 Parameter window "Counter"

Parameter "Debounce time/Min Time"

This parameter is used to set the debounce time. Debouncing prevents unwanted multiple operation of the input, e.g. due to bouncing of the contact.

Options: **10ms/20ms/...../150ms/Min. operation**

The "Min. operation" can be set in Fig.5.4.2.1(1).

Parameter "Enable differential counter"

The parameter set whether enable the differential counter.

When enabled, the parameters related to differential counting is displayed.

Parameter "Pulse detection on"

The parameter set how the input pulse is generated. Options:

Closing contact (rising edge)

Opening contact (falling edge)

Both (rising and falling)

If "Closing contact (rising edge)" is selected, the input pulse is only generated with a closing contact (rising edge).

If "Opening contact (falling edge)" is selected, the input pulse is only generated with a opening contact (falling edge).

If "Both (rising and falling)" is selected, the input pulse is generated with a opening contact (falling edge) and a closing contact (rising edge).

Parameter "Send object values after voltage recover"

The parameter set whether the device sends the object value "Mcounter: Counter value" on the bus after bus voltage recover. If the differential counter has been enabled, it also sends the object value "Dcounter: Counter value" on the bus. Options:

Yes

No

The main and differential counters are reset to the starting value in the bus voltage failure.

Parameter "Cyclically send counter value: Base × Factor"

The parameter is used to set the interval time between two telegrams that are sent cyclically.

Transmission cycle time=Base ×Factor.

Base options: **100ms/1s/1min/1h**

Factor options: **1...255**

Note:**Counting rules (the mode of counter):**

If a decrementing counter is defined with the parameter “factor: one counter step changes counter value by [-10000...10000]”, namely negative counting, the initial value is for the high limit value. The device counts from the high limit to low limit. When the count value is less than low limit value, it will overflow. Then the new count value=the count value – the low limit value + the high limit value +1, and the device will start continually counting from the new count value.

If an incrementing counter is defined with the parameter “factor: one counter step changes counter value by [-10000...10000]”, namely positive counting, the initial value is for the low limit value. The device counts from the low limit to high limit. When the count value is greater than the high limit, it will overflow. Then the new count value=the count value - the high limit value + the low limit value -1, and the device will start continually counting from the new count value.

The application program automatically compares the counter limit value1 and limit value 2, looks for the high limit value from both set limits, and commences to count up or down to suit the counting direction. (About the high / low limit value parameters are described below). The mode of counter is the same for the main and differential counter.

It is important to ensure that both limit values are set to different values. If identical end limit values are entered the behaviour of the counter cannot be defined.

When disable the counter function, both input scanning and object in/out are disabled. Any input status change will be ignored.

Main Counter**Parameter “Data width of counter”**

The data width of the main counter is selected with this parameter. The counting range and the data type of the object “Mcounter: Counter value” depend on this parameter setting. Options:

1byte [0...255]

2byte [-32768...32767]

2byte [0...65535]

4byte [-2147470000...2147470000]

Parameter “Send counter value on change”

This parameter is used to select if a change of the counter state is to be sent for the main counter.

Parameter “Send counter value cyclically”

This parameter is used to determine if the counter values are to be sent cyclically on the bus for

the main counter. The interval time between two telegrams that are sent cyclically to be set with the parameter "Cyclically send counter value: Base × Factor". Options:

Yes

No

Parameter "Counter limit value 1/2"

The parameter is used to set the counter limit value. The limit value 1 is preset for every data type to 0. The limit value 2 is preset which depend on the data width of main counter selected, and the input field of limit value 2 can be freely edited.

Parameter "Mode of counter"

The mode of counting of the counter is set with this parameter. Options:

Normal+1

Manual set

If "Normal+1" is selected, the counter value is incremented by one with generated a input pulse;

If "Manual set" is selected, the following two parameters appear.

Parameter "Divider: number of input pulse for one counter step [1...10000]"

The parameter is visible if the option manual set has been selected with the parameter mode of counter. It is used to set the number of input pulses required to generate a counter pulse for the main and differential counter. For example, the counter states are incremented by 1 after 5 input pulses.

Options: **1 ... 10000**

Parameter "Factor: one counter step changes counter value by [-10000...10000]"

The parameter is visible if the option manual set has been selected with the parameter mode of counter. It is used to set the level of change on the counter state with each counter pulse for the main and differential counter. Options: **-10000...10000**

Negative entry e.g. -5, defines a decremting counter, e.g. -100...0.

Positive entry e.g. 10, defines an incrementing counter, e.g. 0...100

Differential Counter

Parameter "Data width of counter"

The data width of the differential counter is selected with this parameter. The counting range and the data type of the object "DCounter: Counter value, X" depend on this parameter setting. Options:

1byte [0…255]

2byte [-32768…32767]

2byte [0…65535]

4byte [-2147470000…2147470000]

Parameter "When counter crossing limit value"

This parameter sets the reaction when a limit value is reached. Options:

Continue circular counting

Stop until reset

If "Continue circular counting" is selected, the counter continues circular counting. If the actual value falls below the low limit value (only possible with a decrementing counter) or exceeds the high limit value (only possible with an incrementing counter), the new count value is set to the start count value and the pulse count is continued. The new count value is described in the above chapters.

If "Stop until reset" is selected, the counter stops counting and waits for a reset. If the actual value falls below the low limit value (only possible with a decrementing counter) or exceeds the high limit value (only possible with an incrementing counter), the object "Dcounter: stop" will send telegram "0" on the bus, and the counter stops counting, until the counter value is reset or the object "Dcounter: stop" receiving telegram "1". If the object "Dcounter: stop" receiving telegram "1", the counter continues circular counting from the new count value. If the counter value is reset, it will count from the initial value of the parameter. The new count value is described in the above chapters.

Parameter "Send counter value on change"

This parameter is used to select if a change of the counter state is to be sent for the differential counter.

Parameter "Send counter value cyclically"

This parameter is used to determine if the counter values are to be sent cyclically on the bus for the differential counter. The interval time between two telegrams that are sent cyclically to be set with the parameter "Cyclically send counter value: Base × Factor".

Parameter "Counter limit value 1/2"

The parameter is used to set the counter limit value 1/2. The limit value 1/2 are preset which depend on the data width of differential counter selected, and the input field of limit value 1/2 can be freely edited.

Parameter "Mode of counter"

The parameter indicates the counting mode of differential counter is the same with the main counter.

5.4.2.7. Multiple operation

Parameter window “Multiple operation” can be shown in Fig. 5.4.2.7. It is visible when function of the channel “Multiple operation” is selected. If the input is operated several times within a defined period, a defined object value can be modified by the number of operations. In this manner for example, different light scenes are possible by multiple pushes of a button.

Function of the channel	Multiple operation
Description (max 30char.)	
Connect contact type	<input type="radio"/> Normally open <input checked="" type="radio"/> Normally closed
Max. number of operations (=Num. of objects)	2-fold operation
Value send (object tele. operation ...-fold)	On
Value on every operation send	<input checked="" type="checkbox"/>
Max. time between two operation	1 s
Additional object for long operation	<input checked="" type="checkbox"/>
Long operation after	0.5 s
Value send (objectTele. long operation)	TOGGLE
Debounce time	50 ms

Fig. 5.4.2.7 Parameter window “Multiple operation”

Parameter “Connect contact type”

This parameter is used to set whether the input contact is a normally closed or normally open contact. Options:

Normally open

Normally closed

The parameters that are described in this chapter are based on normally open connect type as example, the normally closed connect type is just opposite.

Parameter “Max. number of operations [=Num. of objects]”

This parameter is used to set the max. number of operations. The number is equal to the “Output X-fold” of communication objects. Options:

Single operation

2-fold operation

3-fold operation

4-fold operation

The following describes in detail (3- fold operation as an example, the value send for toggle):

If the option 3-fold operation is selected, there are three objects value appear, and they are not independent, meanwhile they send value according to a certain sequence (1-fold -> 2-fold -> 3-fold). In order to state clear, the following parameter "Value on every operation" set YES, if operation count reach Max. number of operations in a certain time (every operation time <1s), the first time of reach Max. number of operations, 3-fold send the same value with 1-fold and 2 -fold, and the next time, 3 fold will carry out toggle action. In the certain time, if you don't reach Max. number of operations, the next operation will generate a new fold from 1-fold, and carry out toggle action. The following two forms state process of operation:

Operation	OP		OP		OP		OP		OP
Time		<1s		<1s		<1s		<1s	
Object	1f		2f		3f		3f_T		3f_T
Object value	1		1		1		0		0

NOTE: OP: operation

1f: 1-fold object 2f: 2-fold object 3f: 3-fold object

3f_T: 3-fold object value toggle

Operation	OP		OP		OP		OP		OP
Time		>1s		<1s		<1s		<1s	
Object	1f		1f_T		2f		3f		3f_T
Object value	1		0		0		0		1

NOTE:

OP: operation

1f: 1-fold object 2f: 2-fold object 3f: 3-fold object

1f_T: 1 -fold object value toggle**3f_T: 3-fold object value toggle**

If the parameter "Value on every operation" set NO, It will send the last object value after Max. time (Be set in following parameter) elapsed.

Parameter "Value send (object "Tele. Operation ... - fold")"

This parameter sets which object value is to be sent. The settings ON, OFF and Toggle are possible.

With Toggle the current object value is inverted. Options:

On

Off

Toggle

Parameter "Value on every operation send"

The parameter sets whether the respective object value is updated and sent with each operation.

Options:

Yes

No

When enabled, the object value is updated and sent with each operation. With "3-fold operation" as an example, the object "output 1-fold" (after 1st operation) 、 "output 2-fold" (after the 2nd operation) and "output 3-fold" (after the 3rd operation) are sent.

When disabled, the last object value will be sent after Max. time between two operation elapsed.

Parameter "Max. time between two operation"

This parameter sets the maximum allowed interval time between two operations. If no further operations occur within this time, a new fold will be generated from 1-fold with the next operation.

Options:

0.3s

0.5s

...

10s

Parameter "Additional object for long operation"

The parameter sets whether additional communication object for long operation.

When enabled, the following two parameters appear.

Parameter "Long operation after"

This parameter is visible if the parameter "additional object for long operation" is "enable", it is defines the period T_L here, after which an operation is interpreted as "long".

Options: **0.3s/0.5s/...../10s**

Parameter "Value send (object "Tele. Long Operation")"

This parameter is visible if the parameter "additional object for long operation" is "Yes". It is used to set the value of object "output long-fold" that is to be sent on the bus with longer operation of input. The settings ON, OFF and Toggle are possible. With Toggle the current object value is inverted.

Options:

On

Off

Toggle

Parameter "Denounce time"

This parameter is used to set the debounce time. Debouncing prevents unwanted multiple operation of the input, e.g. due to bouncing of the contact. Options: **10ms/20ms/...../150ms**

5.4.2.8. Shutter Control

Parameter window “Shutter control” can be shown in fig. 5.4.2.8. It is visible when function of the channel “shutter control” is selected. The function enables the operation of blinds and shutters with buttons or switches.

Function of the channel	Shutter control ▼
Description (max 30char.)	<input type="text"/>
Connect contact type	<input type="radio"/> Normally open <input checked="" type="radio"/> Normally closed
Operation functionality type	1-push-button,short=stepping,long=moving ▼
Short:Lamella Long :Move UP/DOWN	Note about fuctionality
Long operation after	0.5 ▼ s
Debounce time	50 ▼ ms

Fig.5.4.2.8 Parameter window “Shutter control”

Parameter “Connect contact type”

This parameter is used to set whether the input contact is a normally closed or normally open contact. Options:

Normally open

Normally closed

The parameters that are described in this chapter are based on normally open connect type as example, the normally closed connect type is just opposite.

Parameter “Operation functionality type”

This parameter sets the shutter operating functionality type, which overview is provided in the following tables.

1-push-button,short=stepping, long=moving	
Short operation	Alternate implement “Stop/Adjust upward” or “Stop/Adjust downward” operation. (alternate send the value of the object “0”and“1”)
Long operation	Alternate implement “Move up” or “Move down” operation. (alternate send the value of the object “0”and“1”)

1-push-button, short=moving, long=stepping	
Short operation	Alternate implement "Move up" or "Move down" operation (alternate send the value of the object "0"and"1")
Long operation	Alternate implement "Stop/Adjust upward" or "Stop/Adjust downward" operation (alternate send the value of the object "0"and"1")
1-push-button-operation, moving	
On operation	When operation, send the command in sequence: ->Move up ->Stop/Adjust upward ->Move down ->Stop/Adjust downward->.....
1-switch-operation, moving	
Start of operation (contact closed)	Alternate implement "Move up" or "Move down" operation (alternate send the value of the object "0"and"1")
End of operation (contact open)	Stop/Adjust
2-push-button, standard	
Short operation	"Stop/Adjust upward" or "Stop/Adjust downward" (set by parameter)
Long operation	"Move up" or "Move down" (set by parameter)
2-push-button, moving[shutter]	
On operation	When operation, send the command in sequence: ->Move up ->Stop/Adjust upward ->.....or ->Move down ->Stop/Adjust downward ->..... (Move up/down set by parameter)
2-push-button, stepping	

On operation	<p>“Stop/ Adjust upward” or “Stop/ Adjust downward”</p> <p>(set by parameter)</p> <p>(keep pressing the button can send cyclic)</p>
2-switch-operation, moving[shutter]	
Start of operation	<p>“Move up” or “Move down” (set by parameter)</p>
End of operation	<p>“Stop / Adjust upward” or “Stop / Adjust downward” (the sending value is identical to the value that the operation starting)</p>

Parameter “Tele. STOP/lamella adj”Cyclical send”

It is visible if the shutter control type is “1-push-button,short=moving long=stepping”and“2-push-button, stepping”. It is able to set the interval time of sending the object “stop/adjust adj.” cyclical.

Options: **0.3s/0.5s/.../10s**

Parameter “Reaction on short operation”

It is visible if the shutter control type is “2-push-button, standard”. This parameter defines the operation with short operation. Options :

Stop/lamella up

Stop/lamella down

Parameter “Reaction on long operation”

It is visible if the shutter control type is “2-push-button, standard”. This parameter defines the operation with long operation. Options:

Move up

Move down

Parameter “Reaction on operation”

It is visible if the shutter operation functionally type is “2-push-button,moving[shutter]”, “2-switch-operation, moving [shutter]” and “2-push-button, stepping”. It is defines the action when operation. Different operation functionally type makes different operate action. The former two

operations functionally type is move up and down; the last operation functionally type is stop/lamella reaction.

Options:

Move up

Move down

Options:

Stop/lamella up

Stop/lamella down

Parameter "Long operation after"

This parameter is visible if long operation activate, it is defines the period T_L here, after which an operation is interpreted as "long". Options: **0.3s/0.5s/.../10s**

Parameter "Denounce time"

This parameter is used to set the debounce time. Debouncing prevents unwanted multiple operation of the input, e.g. due to bouncing of the contact. Options: **10ms/20ms/.../150ms**

Chapter 6 Description of communication object

The communication object is the medium to communicate other device on the bus, namely only the communication object can communicate with the bus. The communication object and the object in each channel are the same, using channel A as the example to introduce the function of each communication object in the following.

6.1. Communication object “Manual/Automatic”

Note: “C” in “Flag” column in the below table means that the object has a normal link to the bus; “W” means the object value can be modified via the bus; “R” means the value of the object can be read via the bus; “T” means that a telegram is transmitted when the object value has been modified; “U” means that value response telegrams are interpreted as a write command, the value of the object is updated.

	Number	Name	Object Function	Description	Group Address	Length	C	R	W	T	U	Data Type	Priority
↕	33	General	Man./Auto.			1 bit	C	-	W	-	-	enable	Low
↕	34	General	Man./Auto., Status			1 bit	C	-	-	T	-	enable	Low
↕	35	General	In operation			1 bit	C	R	-	T	-	switch	Low

Fig.6.1 Communication object “General”

No.	Function	Object name	Data type	flags	DPT
33	Man./Auto	General	1bit	C,W	1.003 DPT_Enable
The object is used to disable and enable the manual/automatic button. Telegram value 0 disable the manual/automatic button 1 enable the manual/automatic button					
34	Man/Auto Status	General	1bit	C,T	1.003 DPT_Enable
The object is used to send the status report after man/auto operation status changed. Telegram value 0 the current status for automatic operation 1 the current status for manual operation					
35	In operation	General	1bit	C,R,T	1.001 switch
The communication object is used to periodically send a telegram “1” to the bus to indicate that the device is working properly.					

Table 6.1 Communication object table “General”

6.2. Communication object “Channel setting - Rocker”

6.2.1. Communication object “Dimming”

The communication object “Dimming” can be shown in Fig. 6.2.1.

Number	Name	Object Function	Description	Group Address	Length	C	R	W	T	U	Data Type	Priority
1	Channel A&B - ...	Disable			1 bit	C	-	W	-	-	enable	Low
2	Channel A&B - ...	Dimming			4 bit	C	-	-	T	-	dimming control	Low
3	Channel A&B - ...	Switch			1 bit	C	-	-	T	-	switch	Low

Fig.6.2.1 Communication object “Dimming”

No.	Function	Object name	Data type	flags	DPT
1	Disable	Channel X&Y- {...}	1bit	C,W	1.003 enable
<p>When enable the rocker channel function, this communication object will be active to disable/enable the rocker channel function.</p> <p>Telegram value 0 disable the function 1 enable the function</p> <p>All objects of the function are ineffectiveness when the function is disabled. The function default to enable after bus voltage recovery. (The object “disable” is the same for all rocker operation modes of the channel.)</p> <p>The name in parentheses changes with the parameter “Description (max 30char.)”. If description is empty, display “Channel X&Y-{{...}}” by default. The same below.</p>					
2	Dimming	Channel X&Y- {...}	4bit	C,T	3.007 dimming control
<p>This communication object is used to send dimming command to dim up or dim down. It can make the dimming device on the bus to carry out relative dimming. It will send a stop command to stop dimming when the operation is end.</p>					
3	Switch	Channel X&Y- {...}	1bit	C,T	1.001 switch
<p>This communication object is used to send switch command.</p> <p>Telegram value 0 OFF 1 ON</p>					

Table 6.2.1 Communication object table “Dimming”

6.2.2. Communication object “shutter”

The communication object “Rocker channel - [Shutter]” can be shown in Fig. 6.2.2.

	Number	Name	Object Function	Description	Group Address	Length	C	R	W	T	U	Data Type	Priority
↕	1	Channel A&B - ...	Disable			1 bit	C	-	W	-	-	enable	Low
↕	2	Channel A&B - ...	Up/Down			1 bit	C	-	-	T	-	up/down	Low
↕	3	Channel A&B - ...	Stop			1 bit	C	-	-	T	-	step	Low

Fig.6.2.2 Communication object “Shutter”

No.	Function	Object name	Data type	flags	DPT
2	Up/Down	Channel X&Y- {...}	1bit	C,T	1.008 up/down
This communication object is used to send a shutter moving command (up or down) to the bus. Telegram value 0 move up 1 move down					
3	Stop	Channel X&Y- {...}	1bit	C,T	1.007 step
This communication object is used to send a stop shutter moving command. Telegram value 0 stop moving 1 stop moving					

Table 6.2.2 Communication object table “Shutter”

This communication object is only visible if the parameter Distinction between long and short operation = enable, and the parameter Number of objects for short/long object operation= 2. This additional communication object is assigned to the long operation.

Telegram value	0	OFF
	1	ON

Table 6.3.1 Communication object table "Switch"

6.3.3. Communication object "Value/force output"

There are many data types and communication objects, it will not list in Fig.6.3.3. The communication objects of different data types have the same operation that are transmit the object value, which the range of transmit object value are different. It is possible to distinguish a long/short operation or not, the two objects enable when distinguished.

	Number	Name	Object Function	Description	Group Address	Length	C	R	W	T	U	Data Type	Priority
➡	1	Channel A - ...	Disable			1 bit	C	-	W	-	-	enable	Low
➡	2	Channel A - ...	Close, 1bit			1 bit	C	-	-	T	-	switch	Low
➡	3	Channel A - ...	Open, 1bit			1 bit	C	-	-	T	-	switch	Low

No distinction between long and short operation

	Number	Name	Object Function	Description	Group Address	Length	C	R	W	T	U	Data Type	Priority
➡	1	Channel A - ...	Disable			1 bit	C	-	W	-	-	enable	Low
➡	2	Channel A - ...	Short, 1bit			1 bit	C	-	-	T	-	switch	Low
➡	3	Channel A - ...	Long, Recall scene			1 byte	C	-	-	T	-	scene control	Low

Distinction between long and short operation

Fig.6.3.3 Communication object "Value/Forced output"

No.	Function	Object name	Data type	flags	DPT
2	Short/Close, 1bit	Channel X-	1bit	C,T	1.001 DPT_Switch
	Short/Close, 1byte signed	{{...}}	1byte		6.010 DPT_Value_1_Count
	Short/Close, 1byte unsigned		1byte		5.010 DPT_Value_1_Ucount
	Short/Close, Recall scene		1byte		18.001 DPT_SceneControl
	Short/Close, Store scene		1byte		18.001 DPT_SceneControl
	Short/Close, 2byte signed		2byte		8.001 DPT_Value_2_Count
	Short/Close, 2byte unsigned		2byte		7.001 DPT_Value_2_Ucount
	Short/close, Temperature		2byte		9.001 DPT_Value_Temp
	Short/Close, 3byte		3byte		10.001 DPT_TimeOfDay
	Short/Close, 4byte signed value		4byte		12.001
	Short/Close, 4byte unsigned value				DPT_Value_4_Ucount

This communication object is used to transmit the input value. It is only transmit the object value in short operation if distinguish a long and short operation. It will transmit the object value in rising edge if no distinction between long and short operation. The object value range depend on the data type, The data type is set in the parameter "Reaction on short operation/close the contact".

3	Long/Open, 1bit	Channel X-	1bit	C,T	1.001 DPT_Switch
	Long/Open, 1byte signed	{{...}}	1byte		6.010 DPT_Value_1_Count
	Long/Open, 1byte unsigned		1byte		5.010 DPT_Value_1_Ucount
	Long/Open, Recall scene		1byte		17.001 DPT_SceneControl
	Long/Open, Store scene		1byte		18.001 DPT_SceneControl
	Long/Open, 2byte signed		2byte		8.001 DPT_Value_2_Count
	Long/Open, 2byte unsigned		2byte		7.001 DPT_Value_2_Ucount
	Long/Open, Temperature		2byte		9.001 DPT_Value_Temp
	Long/Open, 3byte		3byte		10.001 DPT_TimeOfDay
	Long/Open, 4byte signed value		4byte		13.001 DPT_Value_4_Count
	Long/Open, 4byte unsigned value		4byte		12.001 DPT_Value_4_Ucount

This communication object is used to transmit the input value. It is only transmit the object value in long operation if distinguish a long and short operation. It will transmit the object value in falling edge if no distinction between long and short operation. The object value range depend on the data type, The data type is set in the parameter "Reaction on long operation/open the contact".

Table 6.3.3 Communication object table "Value/Forced output"

6.3.4. Communication object “Scene control”

The communication object “Scene control” will be shown in Fig.6.3.4. The actuator groups can be controlled via max. 6 individual objects, which provided 3 data types.

	Number	Name	Object Function	Description	Group Address	Length	C	R	W	T	U	Data Type	Priority
➡	1	Channel A - ...	Disable			1 bit	C	-	W	-	-	enable	Low
➡	2	Channel A - ...	Store scene			1 bit	C	-	W	T	-	boolean	Low
➡	3	Channel A - ...	1bit, Group A			1 bit	C	-	W	T	U	switch	Low
➡	4	Channel A - ...	1bit,Group B			1 bit	C	-	W	T	U	switch	Low
➡	5	Channel A - ...	1bit, Group C			1 bit	C	-	W	T	U	switch	Low
➡	6	Channel A - ...	1bit,Group D			1 bit	C	-	W	T	U	switch	Low
➡	7	Channel A - ...	1bit,Group E			1 bit	C	-	W	T	U	switch	Low
➡	8	Channel A - ...	1bit,Group F			1 bit	C	-	W	T	U	switch	Low

Fig.6.3.4Communication object “Scene control”

No.	Function	Object name	Data type	flags	DPT
2	Store scene	Channel X- {{...}}	1Bit	C,W,T	1.002 boolean
<p>The communication object is used to store scene, if as soon as a long operation is detected and the object has the value “1” or only the object receives the value “1”, storing is activated. If the object receives or sends the value “0”, storing is ended. The storage manners of scene are described in the parameter setting chapter.</p>					
3~8	1bit/1byte/2byte/Temperature, Group-A...F	Channel X- {{...}}	1bit 1byte 1byte 2byte	C,W, T,U	1.001 DPT_Switch 5.001 DPT_Scaling 5.010 DPT_Value_1_Ucount 9.001 DPT_Value_Temp
<p>The communication object is used to control the actuator group, it can control by a 1 bit, 8 bit data or 16 bit data (set by parameter). When saving the scene, the object “(1bit/8bit) , group A...E” will be read, and which can be modified and storage on the bus. After the bus voltage recovery, the value of the object resume to the default value and the new storage value will be lost.</p>					

Table 6.3.4 Communication object table “Scene control”

6.3.5. Communication object “Switching sequence”

The communication object “Switching sequence” will be shown in Fig.6.3.5. It can modify the object value with an operation step by step. An object corresponds to one switch level.

Number	Name	Object Function	Description	Group Address	Length	C	R	W	T	U	Data Type	Priority
1	Channel A - ...	Disable			1 bit	C	-	W	-	-	enable	Low
2	Channel A - ...	Output level-1			1 bit	C	-	-	T	-	switch	Low
3	Channel A - ...	Output level-2			1 bit	C	-	-	T	-	switch	Low
4	Channel A - ...	Output level-3			1 bit	C	-	-	T	-	switch	Low
5	Channel A - ...	Output level-4			1 bit	C	-	-	T	-	switch	Low
6	Channel A - ...	Output level-5			1 bit	C	-	-	T	-	switch	Low
7	Channel A - ...	Level increment/decrement			1 bit	C	-	W	-	-	step	Low

Fig.6.3.5 Communication object “Switching sequence”

No.	Function	Object name	Data type	flags	DPT
2~6	Output level-x(x=1~5)	Channel X- {{...}}	1bit	C,T	1.001 switch
<p>The number of the communication object (maximum 5) which the levels of switch are set by parameter “No. of object”. The communication object sent on the bus is the object which one of binary code is modified, which the bit of the binary code had been changed. The objects are detailed description in the switching sequence parameter chapter.</p>					
7	Level increment/decrement	Channel X- {{...}}	1bit	C,W	1.007 step
<p>The communication object “level increment/decrement” is used to increase/decrease the level of the switch. It will increase one level when receiving “1” and decrease a level when receiving “0”. The object is detailed description in the switching sequence parameter chapter.</p>					

Table 6.3.5 Communication object table “Switching sequence”

6.3.6. Communication object “Counter”

The communication object “Counter” will be shown in Fig.6.3.6. Including main counter and differential counter communication object, both these communication objects will start count when the input pulse is generated with an operation. The data width which has been selected for both counters can be set to same or different. But the counting is independent of each other.

Number	Name	Object Function	Description	Group Address	Length	C	R	W	T	U	Data Type	Priority
1	Channel A - ...	Disable			1 bit	C	-	W	-	-	enable	Low
2	Channel A - ...	MCounter:Counter value			2 bytes	C	-	-	T	-	pulses	Low
3	Channel A - ...	DCounter:Counter value			2 bytes	C	-	-	T	-	pulses difference	Low
4	Channel A - ...	DCounter:Limit exceeded			1 bit	C	-	-	T	-	alarm	Low
5	Channel A - ...	DCounter:Reset value			1 bit	C	-	W	-	-	reset	Low
6	Channel A - ...	DCounter:Stop			1 bit	C	-	W	T	-	start/stop	Low
7	Channel A - ...	MCounter:Limit exceeded			1 bit	C	-	-	T	-	alarm	Low
8	Channel A - ...	Request counter value			1 bit	C	-	W	-	-	enable	Low

Fig.6.3.6 Communication object “Counter”

No.	Function	Object name	Data type	flags	DPT
2	MCounter: Counter value	Channel X- {...}	1byte	C,T	5.010 DPT_Value_1_Ucount
			2byte		8.001 DPT_Value_2_Count
			2byte		7.001 DPT_Value_2_Ucount
			4byte		13.001 DPT_Value_4_Count
<p>This communication object is used to transmit the current counting value of the main counter. The counting range depends on data type, which is defined with the parameter “Date width of counter”.</p>					
3	DCounter: Counter value	Channel X- {...}	1byte	C,T	5.010 DPT_Value_1_Ucount
			2byte		8.001 DPT_Value_2_Count
			2byte		7.001 DPT_Value_2_Ucount
			4byte		13.001 DPT_Value_4_Count
<p>It is visible if enable the parameter “Enable differential counter”. This communication object is used to transmit the current counting value of the differential counter. The counting range depends on data type, which is defined with the parameter “Date width of counter”.</p>					
4	DCounter : Limit exceeded	Channel X- {...}	1bit	C,T	1.005 alarm

When the differential count value exceeded the limit value, the object will send telegram value "1", which report counting overflow.					
5	DCounter: Reset value	Channel X- {...}	1bit	C,W	1.015 reset
The communication object is used to reset the count value of differential counter. When the object receives telegram value "1", the current count value will become count initial value (limit value).					
6	DCounter: Stop	Channel X- {...}	1bit	C,W,T	1.010 start/stop
When the differential counter overflow, the object sends telegram value "0", which report count stopping (set in the parameter). Meanwhile, if the object receives telegram value "0", the differential counter can also stop counting. If the object receives telegram value "1", it will continue counting.					
7	MCounter: Limit exceeded	Channel X- {...}	1bit	C, T	1.005 alarm
When the main count value exceeded the limit value, the object will send telegram value "1", which report counting overflow.					
8	Request Counter value	Channel X- {...}	1bit	C,W	1.003 enable
When the object receives telegram value "1", the objects "MCounter: Counter value, X" and "DCounter: Counter value,X" will send their current value on the bus.					

Table 6.3.6 Communication object table "Counter"

6.3.7. Communication object “Multiple operation”

The communication object “Multiple Operation” will be shown in Fig.6.3.7. If the input is operated several times within a defined period, a defined object value can be modified by the number of operations.

Number	Name	Object Function	Des	Group Adc	Length	C	R	W	T	U	Data Type	Priority
0	Disable , A	CH A Disable			1 bit	C	-	W	-	-	enable	Low
1	Output 1-fold , A	CH A 1-fold			1 bit	C	-	-	T	-	switch	Low
2	Output 2-fold , A	CH A 2-fold			1 bit	C	-	-	T	-	switch	Low
3	Output 3-fold , A	CH A 3-fold			1 bit	C	-	-	T	-	switch	Low
4	Output 4-fold , A	CH A 4-fold			1 bit	C	-	-	T	-	switch	Low

Fig 6.3.7 Communication object “Multiple operation”

No.	Function	Object name	Data type	flags	DPT
2~5	Output x-fold(x=1~4)	Channel X- {...}	1Bit	C,T	1.001 switch
<p>The number of the communication object (maximum 4) is set with the parameter “Max. number of operations(=Num. of objects)”. If the input is operated several times within a defined period, the objects will send the relevant telegram value on the bus, which the telegram value is set with the parameter “value send (object “Tele. Operation...-fold)”. The objects will be described in the multiple operation parameter chapter.</p>					
6	Output Long-fold	Channel X- {...}	1Bit	C,T	1.001 switch
<p>It is visible if parameter “Additional object for long operation” selected “enable”. Once detected a long operation the object will send telegram value on the bus, the telegram is set with the parameter “value send (object “Tele. Long operation)”.</p>					

Table 6.3.7 Communication object table “Multiple operation”

6.3.8. Communication object “Shutter control”

The communication object “Shutter Control” will be shown in Fig.6.3.8.

Number	Name	Object Function	Description	Group Address	Length	C	R	W	T	U	Data Type	Priority
1	Channel A - ...	Disable			1 bit	C	-	W	-	-	enable	Low
2	Channel A - ...	Up/Down			1 bit	C	-	-	T	-	up/down	Low
3	Channel A - ...	Stop/lamella adj			1 bit	C	-	-	T	-	step	Low
4	Channel A - ...	Upper limit position			1 bit	C	-	W	-	-	enable	Low
5	Channel A - ...	Lower limit position			1 bit	C	-	W	-	-	enable	Low

Fig.6.3.8 Communication object “Shutter Control”

No.	Function	Object name	Data type	flags	DPT
2	Up/Down	Channel X- {...}	1Bit	C,T	1.008 up/down
This communication object sends a shutter motion command (up or down) to the bus. Telegram value 0 move up 1 move down					
3	Stop/lamella adj	Channel X- {...}	1Bit	C,T	1.007 step
This communication object sends a stop command or lamella adjustment. Telegram value 0 stop/adjust up 1 stop/adjust down					
4	Upper limit position	Channel X- {...}	1Bit	C,W	1.003 enable
The object is used to upper limit shutter moving. Telegram value 0 no limit moving up 1 limit moving up					
5	Lower limit position	Channel X- {...}	1Bit	C,W	1.003 enable
The object is used to lower limit shutter moving. Telegram value 0 no limit moving down 1 limit moving down					

Table 6.3.8 Communication object table “Shutter Control”